



oRT3 - Real Time Programming with FreeRTOS

Comprehensive FreeRTOS training: from Theory to Practice

Objectives

- Get an overview on Cortex-M4 architecture
- Discover the concepts of real time multitasking
- Understand Real Time constraints
 - Determinism
 - Preemption
 - Interrupts
- Understand the FreeRTOS architecture
- Discover the various FreeRTOS services and APIs
- Learn how to develop FreeRTOS applications
- Learn how to debug FreeRTOS applications

Prerequisites

- Familiarity with embedded C concepts and programming
- Basic knowledge of embedded processors

Course environment

- Theoretical course
 - PDF course material (in English)
 - Course dispensed using the Teams video-conferencing system
 - The trainer to answer trainees' questions during the training and provide technical and pedagogical assistance through the Teams video-conferencing system
- Practical activities
 - Practical activities represent from 40% to 50% of course duration
 - The trainer has access to trainees' Online PCs for technical and pedagogical assistance.
 - Example code, labs and solutions
- Virtual Machine with System Workbench for STM32 with GNU ARM Eclipse QEMU
- Emulated board STM32F4-Discovery

Course duration

- Total: 20 hours
- 4 sessions, 5 hours each (excluding break time)
- From 40% to 50% of training time is devoted to practical activities
- Some Labs may be completed between sessions and are checked by the trainer on the next session

Target Audience

- Any embedded systems engineer or technician with the above prerequisites.

Course Outline

First Session

Cortex-M Overview

- ARMv7-M Architecture
- Cortex-M4 Architecture
- Registers and Execution States
- Privileges, Mode and Stacks
- Reset Behavior
- Exception and Interrupts
- The System Timer
- Memory Model
- Power Management
- STM32F407x Implementation Example

Exercise: Create a new project

Exercise: Interrupt Management

Real-Time Concepts

- Embedded system architectures
- Tasks and process
- Real-Time

Exercise: Context Switch

Second Session

Introduction to FreeRTOS

- The FreeRTOS Family
- FreeRTOS+Ecosystem
- Why use FreeRTOS
- FreeRTOS Code Structure

Scheduling

- Scheduler
- Schedulability

Task Management

- Creating Tasks
- Task Priorities
- Task States
- The idle task
- Delays
- Changing Task Priority
- Deleting Tasks
- Suspending Tasks
- Kernel Structures
- Thread Local Storage
- Kernel Interrupts on Cortex-M4
- Scheduling Traces

- Visual trace diagnostics using Tracealyzer

Exercise: Task Management

Exercise: Periodic Tasks

Exercise: Task Statistics

Third Session

Memory Management in FreeRTOS

- FreeRTOS Memory Managers
- Out of Memory management
- Stack overflow detection

Exercise: Context Switch Measurement

Resource Management

- Mutual Exclusion
- Critical Sections
- Mutexes
- Gatekeeper Tasks
- Lock-Free Data Structures

Exercise: Resource Management

Synchronization Primitives

- Queues
- Queues Sets
- Synchronization
- Events and Event Groups
- The Readers/writer problem
- Using Other Primitives within an ISR

Exercise: Queue Management

Exercise: Readers Writer Problem

Fourth Session

Interrupt Management

- Tasks and Interrupts
- FreeRTOS Binary and Counting Semaphores
- Task Notifications
- Stream Buffers
- Message Buffers
- Interrupt Nesting
- Low Power Support

Exercise: Interrupt Management

Exercise: Tickless Mode

Software Timer

- Software Timers
- Deferred Interrupt Handling

Exercise: Implement Soft Timers

Exercise: Software Timer Management

FreeRTOS-MPU

- The Cortex-M MPU
- The FreeRTOS-MPU Port
- Defining MPU Regions
- Creating User and System Tasks
- Practical Usage Tips

Appendix

Data Structures

- FIFO
- Linked list

Memory Management and Real-Time

- Memory Management
- Memory Errors

CMSIS-RTOS

- Overview
- Kernel Information and Control
- Threads Management
- Generic Wait Functions
- Communication and Resource Sharing
 - Semaphores
 - Mutex
 - Message Queue
 - Signal Events
 - Event Flags
 - Memory Pool
 - Mail Queue
- Timer Management
- Interrupt Service Routines