



STG - STM32 + FreeRTOS + LwIP

This course covers the STM32 ARM-based MCU family, the FreeRTOS Real Time OS, the LWIP TCP/IP Stack and/or the EmWin GUI Stack

Objectives

- Get an overview on the Cortex-M architecture
- Understand the Cortex-M software implementation and debug
- Learn how to deal with interrupts
- Get an overview on STM32F4 architecture
- Describing the units which are interconnected to other modules, such as clocking, interrupt controller and DMA controller
- Describing some independent I/O modules like the ADC and GPIOs
- Getting started with the ST Drivers to program STM32 peripherals (The STM32Cube Library or ST Standard Peripheral Library)
- Understand the FreeRTOS architecture
- Discover the various FreeRTOS services and APIs
- Learn how to develop and debug FreeRTOS applications
- Getting started with the LwIP TCP/IP stack (Describing the STM32 Ethernet Controller, having a look on porting, describing the parameterizing, and developing application based on UDP and TCP protocols) (not available for STM32F0 family)
- The peripherals overview presented in this course can be detailed upon request ([STR9 - STM32 Peripheralscourse](#))

This course can be based on STM32F4xx, STM32F2xx, STM32F1xx, or STM32F0xx families

On request TouchGFX and EmWin can be added in a specific training

Course environment

- Convenient course material
- Example code, labs and solutions
- A STM32-Eval Board (like the STM3240G-Eval Board (Cortex-M4)) with the SW4STM32 IDE (Keil, IAR or Trace32 (Lauterbach) can also be used)

Prerequisites

- Familiarity with C concepts and programming targeting the embedded world
- Basic knowledge of embedded processors
- Basic knowledge of multi-task scheduling
- The following courses could be of interest:
 - [AAM - ARM Cortex-M Architecture \(v7/v8\)course](#)
 - [STR7 - STM32 F4-Series implementationcourse](#)
 - [L2 - C language for Embedded MCUscourse](#)
 - [L3 - Embedded C++course](#)
 - [STR9 - STM32 Peripheralscourse](#)

Target Audience

- Any embedded systems engineer or technician with the above prerequisites.

Course Outline

First Day

Cortex-M Architecture Overview

- V7-M Architecture Overview
- Core Architecture
 - Harvard Architecture, I-Code, D-Code and System Bus
 - Write Buffer
 - Bit-Banding
 - Registers (Two stacks pointers)
 - States
 - Different Running-modes and Privileged Levels
 - System Control Block
 - SysTick Timer
 - MPU Overview
- Programming
 - Alignment and Endianness
 - CMSIS Library
- Exception / Interrupt Mechanism Overview
 - Vector Table
 - Interrupt entry and return Overview
 - Tail-Chaining
 - Pre-emption (Nesting)
 - NVIC Integrated Interrupt Controller
 - Exception Priority Management
 - Fault escalation
- Debug Interface

Exercise: Becoming familiar with the IDE and clarifying the boot sequence

Exercise: Cortex-M4 Mode Privilege (with CMSIS library)

Exercise: Cortex-M4 Exception Management (put in evidence tail-chaining/nesting)

Exercise: Cortex-M4 MPU

STM32F4 MCUs Architecture Overview

- ARM core based architecture
- Description of STM32Fx SoC architecture
- Clarifying the internal data and instruction paths: Bus Matrix, AHB-lite interconnect, peripheral buses, AHB-to-APB bridges, DMAs
- Memory Organization
 - Flash memory read interface
 - Adaptive Real-Time memory accelerator, instruction prefetch queue and branch cache
 - Sector and mass erase
 - Concurrent access to RAM blocks
- SoC mapping
- Flash Programming methods
- Boot Configuration

Second Day

Reset, Power and Clocking

- Reset
 - Reset sources
 - Boot configuration, physical remap
 - Embedded boot loader
- Clocking
 - Clock sources, HSI, HSE, LSI, LSE
 - Integrated PLLs
 - Clock outputs
 - Clock security system
- Power control
 - Power supplies, integrated regulator
 - Battery backup domain, backup SRAM
 - Independent A/D converter supply and reference voltage
 - Power supply supervisor
 - Brownout reset
 - Programmable voltage detector
- Low power modes
 - Entering a low power mode, WFI vs WFE
 - Sleep mode
 - Stop mode
 - Standby mode

Exercise: Configure the system to measure the current consumption in different low-power modes

Exercise: How to configure the programmable BOR thresholds using the FLASH option bytes

Exercise: How to enter the Standby mode and wake up from this mode by using an external reset/WKUP pin

Exercise: How to enter the Stop mode and wake up from this mode by using the RTC wakeup timer event or an interrupt

ST Firmware Library Description

DMA

- Dual AHB master bus architecture, one dedicated to memory accesses and one dedicated to peripheral accesses
- 8 streams for each DMA controller, up to 8 channels (requests) per stream
- Priorities between DMA stream requests
- FIFO structure
- Independent source and destination transfer width
- Circular buffer management
- Double buffer mode
- DMA1 and DMA2 request mapping

Exercise: DMA FIFO mode

Exercise: Flash To RAM using DMA

Hardware implementation

- Power pins
- Pinout
 - Pin Muxing, alternate functions
- GPIO module
 - Configuring a GPIO
 - Speed selection
 - Locking mechanism
 - Analog function

- Integrated pull-up / pull-down
- I/O pin multiplexer and mapping
- System configuration controller
 - I/O compensation cell
 - External Interrupts / Wakeup lines selection
 - Ethernet PHY interface selection
- External Interrupts

Exercise: Configure an external Interrupt

12-bit Analog-to-Digital Converter

- 12-bit, 10-bit, 8-bit or 6-bit configurable resolution
- Regular channel group vs Injected channel group
- Single and continuous conversion modes
- Scan mode
- External trigger option with configurable polarity for both regular and injected conversions
- Discontinuous mode
- Analog watchdog
- Dual/Triple mode (on devices with 2 ADCs or more)
- Configurable delay between conversions in Dual/Triple interleaved mode
- DMA request generation during regular channel conversion

Exercise: Get voltage from the potentiometer using, DMA transfer generation, display the result on LCD screen

Optional: Timers Overview

- Advanced-control timers TIM1 and TIM8
 - 16-bit up, down, up/down auto-reload counter; 16-bit programmable prescaler
 - Input Capture, Output Compare, PWM generation, One-pulse mode
 - Synchronization circuit/ Controlling Timers external signals / Interconnecting several timers
 - Interrupt/DMA generation
- Real Time Clock
 - Independent BCD timer/counter; 16-bit programmable prescaler
 - Daylight saving compensation programmable by software
 - Two programmable alarms with interrupt function
 - Automatic wakeup unit
 - Reference clock detection / Digital calibration circuit
 - Tamper detection

Exercise: How to use DMA with TIM1 Update request to transfer Data from memory to TIM1

Exercise: Configuring the RTC

Third Day

The FreeRTOS source code

- Introduction to FreeRTOS
 - The FreeRTOS architecture and features
- Getting FreeRTOS source code
 - Files and directories structure
- Data types and coding style
 - Naming conventions
- FreeRTOS on the Cortex/M processors

Task Management

- Prioritized Pre-emptive Scheduling / Co-operative scheduling
- The Task life-cycle
 - Task Functions

- Creating tasks
- Using the task parameter
- The Task State Machine
- Deleting tasks
- Task Priorities
 - Assigning task priorities
 - Changing task priorities
- The idle task
 - Idle task hook
- Blocking a task for a specific delay
- Editing the FreeRTOSConfig.h header file
- Suspending a task
- The Kernel Structures Overview
- FreeRTOS Debug Capabilities (Hook, Trace)
- Visual trace diagnostics using Tracealyzer

Exercise: Understand the notion of task context and the context switch mechanism

Exercise: Create a debug configuration to debug your program using a FreeRTOS-aware debugging mode

Exercise: Periodic Tasks

Exercise: Task Statistics

Memory Management

- FreeRTOS-provided memory allocation schemes
 - Choosing the heap_x.c file depending on the application
- Adding an application-specific memory allocator
- Checking remaining free memory
- Stack monitoring
- Dimensioning Stack and Heap

Exercise: Direct Context Switch measurement and Stack Overflow Detection

Exercise: Debugging memory

Fourth Day

Queue Management

- Blocking on queue Reads
- Blocking on queue Writes
- Queue Creation
- Sending on a queue
- Receiving from a queue
- Sending compound types
- Transferring large data
- Queue Set Overview/ Blocking on multiple objects
- Semaphores and Events Introduction

Exercise: Synchronizing and communicating between tasks through queues to send datas to a bus communication

Resource Management

- Conflict examples
- Mutual exclusion
- Critical sections
 - Disabling the interrupts
 - Suspending (locking) the scheduler
- Mutexes
 - Mutual exclusion scenario
 - API functions for Mutexes
 - Recursive Mutexes

- Priority inversion
- Priority inheritance
- Deadlock
- Gatekeeper tasks

Exercise: Readers / Writers Problem

Exercise: Producer / Consumer Problem

Exercise: Understand deadlock and starvation

Interrupt Management

- Binary semaphore used for interrupt synchronization
 - API function for binary semaphore
- Counting semaphores
- Using queues within an ISR
- Interrupt Nesting
 - Interrupts on Cortex-M
- Low Power Support

Exercise: Synchronize Interrupts with tasks

Exercise: Low-Power FreeRTOS Support (Tickless Mode)

Fifth Day

Software Timer

- The Timer Daemon Task
- Timer Configuration
- One-shot / Auto-reload Timer
- Software Timer API

Exercise: Understand the use of software timers

FreeRTOS MPU

- User Mode and Privilege Mode
 - Access Permission Attributes
- Defining an MPU region
- Creating a non-privileged task
- Linker configuration
- Practical Usage Tips

STM32 Fast Ethernet Controller Overview

- Architecture of the MAC
- Connection to PHY, RMII / MII
- Transmit and receive FIFO threshold setting
- Multicast and unicast address filtering
- Management interface
- Buffer and Buffer Descriptor organization
- Low level Drivers for STM32

LwIP TCP/IP Stack Presentation

- Overview
- Buffer and memory management
- LwIP configuration options
- Network interfaces
- MAC and IP address settings
- IP processing

- UDP processing
- TCP processing
- Interfacing the stack
- Application Program Interface (API)
 - Standalone
 - Netconn and BSD socket library
- STM32/FreeRTOS Port Overview

Exercise: Run an http server application based on Netconn API of LwIP TCP/IP stack

Exercise: http server application based on Socket API of LwIP TCP/IP stack

Exercise: TCP Echo Client/Server

Exercise: In-Application Programming (IAP) over Ethernet using TFTP or HTTP

Optional : EmWin GUI Stack Presentation

- Library and package description
- How to use the library
 - Configuration
 - Initialization
 - Core functions
 - Developing a multi-task application with EmWin
 - Working with some widgets (as the Windows, Buttons, Multipage, Image, ListBox, CheckBox)
 - Using the EmWinGuiBuilder software

Exercise: Getting started with the emWin stack, create a GUI to control input/output from the touch screen

Optional: TouchGFX

- Basic Application Development
- Advanced Application Development
- Application Configuration
- Widgets
- Integration
- Getting Started with CubeMX and TouchGFX
- Deploying your application using ST-Link

Exercise: How to configure and use TouchGFX under FreeRTOS (Demo)